UNIVERSITI TEKNOLOGI MARA

ANALYSIS OF MICRO-DOPPLER CHARACTERISTICS OF PEDESTRIANS USING MULTIPLE-INPUT MULTIPLE-OUTPUT (MIMO) RADAR FOR ENHANCED TARGET DETECTION

SHAFINAZ BINTI MOHD BASIR

Dissertation submitted in partial fulfillment of the requirement for the degree of

Master of Science

Faculty of Electrical Engineering

January 2017

ABSTRACT

This paper presents a study on micro-Doppler characteristics of pedestrians using multiple-input multiple-output (MIMO) radar designed for automotive radar applications. The signals reflected might be similar in terms of reflecting angle and Doppler spread, between pedestrian and slow moving object. Hence, this study reports on the measurement and characterization of micro-Doppler signatures of the pedestrian in terms of Doppler spread contributed by multi-antenna measurement. The experiment is conducted in an anechoic chamber and laboratory, using continuous wave (CW) signal with the centre frequency of 4 GHz. A pair of ultra-wideband horn antenna is used as the radar sensors and positioned at different points along the baseline to produce pseudo-MIMO configurations. During the measurements, three types of targets are used - a moving object, a swinging ball and a pedestrian. Human target is studied in two motions, walking with swinging arms and walking without swinging arms. Results are analyzed using MATLAB software to generate corresponding Doppler spectrograms, Doppler histograms and Doppler spread analysis. The obtained results indicated the possibility of distinguishing micro-Doppler signatures between moving object and pedestrian by exploiting the difference in their Doppler spread information. Compared to single antenna configurations, wider Doppler spread is obtained when using MIMO configurations. Thus, outcomes from the MIMO configurations may help to improve the target classifications.

ACKNOWLEDGEMENT

First of all, I am greatly indebted to Allah SWT on His blessing to make this project succeed and completed in a proper way. I would like to gratitude and express my appreciations to all the organizations and individuals who have contributed the efforts either directly or indirectly right through my project. With the cooperation from all the parties, the objectives of the project are achieved precisely to the preferred result. Additionally, I would like to give an honoured thanks to my project supervisor, Dr. Idnin Pasya Ibrahim for the supervision with proper guidance and full of cooperation in any phase of the project especially in solving the problems that occurs during the project research. Besides, big thanks are dedicated to my project partner in this research, Tajmalludin Yaakob and technician for Microwave Laboratory, Encik Khalim for their guidance and helps during finishing this study.

Furthermore, I would like to thanks to my parents and family members who had supports me a lot all this year throughout the project with so much loves and cares in term of morals, financial and advices. Lastly, my appreciation goes to all my fellow links in this final year project especially those from Communication Department in Faculty of Electrical Engineering, Universiti Teknologi MARA Shah Alam. Their compliance in giving technical support and suggestions are valued upon the completion this work. This study is successfully done and all the objectives are achievable.

TABLE OF CONTENTS

	Page	
AUTHOR'S DECLARATION	ii	
ABSTRACT	iii	
ACKNOWLEDGEMENT	iv	
TABLE OF CONTENTS	v	
LIST OF TABLES	vii	
LIST OF FIGURES	viii	
LIST OF ABBREVIATIONS AND GLOSSARY		
CHAPTER 1: INTRODUCTION		
1.1 Background of Study	1	
1.2 Problem Statement	5	
1.3 Objectives	5	
1.4 Scope and Limitation of Study	6	
1.5 Significance of Study	6	
1.6 Thesis Organization	6	
CHAPTER 2: LITERATURE REVIEW		
2.1 Automotive Radar	8	
2.2 Works Related to Improvement of Target Detection and Velocity		
Estimation	9	
2.3 MIMO Radar Concept and Potential Applications in Automotive Senso	ors 11	
CHAPTER 3: METHODOLOGY		
3.1 Flow Chart	13	
3.1.1 Determine the MIMO Configurations	16	
3.1.2 Experimental Setup	18	
3.2 Comparison between Walking and Running Pedestrian on the Treadmi	.11	
in the Anechoic Chamber	20	
3.3 Comparison between Swinging Ball and Walking Pedestrian in the		
Anechoic Chamber	23	

3.4	Comparison between Moving Object and Walking Pedestrian in the		
	Laboratory	25	
CHA	APTER 4: RESULT AND DISCUSSION		
4.1	Introduction	27	
4.2	Comparison between Walking and Running Pedestrian on the	Treadmill	
	in the Anechoic Chamber	29	
4.3	Comparison between Swinging Ball and Walking Pedestrian in	n the	
	Anechoic Chamber	32	
4.4	Comparison between Moving Object and Walking Pedestrian	in the	
	Laboratory	36	
4.5	Analysis of Doppler Spread	40	
	4.5.1 Measurement in the Anechoic Chamber	40	
	4.5.2 Measurement in the Laboratory	41	
СНА	APTER 5: CONCLUSION AND RECOMMENDATION		
5.1	Conclusion	45	
5.2	Recommendation for Future Work	46	
REF	ERENCES	47	
APPI	ENDICES	51	