

**MODELING AND SIMULATION ON STARTING RESISTANCE  
OF A DC MOTOR USING MATLAB/SIMULINK**

**This is presented in partial fulfillment for award of Bachelor of  
Electrical Engineering (Honours)  
UNIVERSITI TEKNOLOGI MARA**



**MUHAMMAD ZAMRI BIN RAMLI**  
**Faculty of Electrical Engineering**  
**Universiti Teknologi MARA**  
**40450 Shah Alam, Selangor.**  
**Mei, 2003**

## **ACKNOWLEDGMENT**

In the name of Allah, the Most Beneficent and the Most Merciful. All praises being to Allah, Load of the Universe, with also bless and regard to Nabi Muhammad S.A.W. His companion and the people who follow His path.

The author is gratefully acknowledges his sincere gratitude to Associate Professor Ir. Zulkefli Bin Yaacob for professional guidance and full support to complete this paper successfully.

The author also gratefully acknowledges the co-operation and discussion with my friends in assisting with new idea in developing the project.

I am also would like to thank with my family, my friends on the moral and material support. Gratefully thank to my mother and father.

## ABSTRACT

This thesis presents a modeling and simulated results of the starting resistance of a dc motor. In this project, I shall examine the starting transient of a shunt dc motor. The objectives are to implement the SIMULINK simulation of a dc motor operation in modeling the maximum starting current of  $100 A$  and minimum starting current of  $60 A$ . The simulation measured at variations of load as at no-load, full-load, half-load and quarter-load conditions. This includes the study of dynamic mathematical modeling of a dc motor. The value of resistance will determine its suitability. Matlab/Simulink software is used in modeling and simulating the starting resistance of a dc motor.

# CONTENTS

CHAPTER	DESCRIPTION	PAGE
	DECLARATION	i
	ACKNOWLEDGEMENT	ii
	ABSTRACT	iii
	TABLE OF CONTENTS	iv
	LISTS OF FIGURES	vii
	LISTS OF TABLES	ix
	LIST OF ABBREVIATIONS	x
<b>1</b>	<b>INTRODUCTION</b>	
1.1	Introduction	1
1.2	Physical Construction	3
1.3	Motor Classification	4
1.3.1	Classification by Speed	5
1.3.1.1	Varying Speed	5
1.3.1.2	Adjustable Constant Speed	5
1.3.1.3	Adjustable Variable Speed	5
1.3.1.4	Multi-speed	5
1.3.2	Classification by Construction	6
1.3.2.1	Size or weight	6
1.3.2.2	Usage	6
1.3.2.3	Frame	6
1.3.2.4	Mounting	6

# CHAPTER 1

## INTRODUCTION

### 1.1 Introduction

In the early days, electricity was commonly generated and supplied as direct current for used at dc motors. Nowadays, nearly all-public supplies of electricity are alternating current. However, direct current has many important applications.

For certain purposes the dc motor is the only acceptable machine. This arises when the drive requires automatic speed increase with light load and controlled braking as in electric traction and cranes.

Other applications require continuous control such that the speed may be held at any set value or made to bear a constant relation to other drives. For instance, in continuous rolling processes, steel mills, paper, plastics, textile, hosiery, cable making and so on.

DC machines can be thought of as a dying breed, but death will come slowly. Prior to the development of reliable, high-power solid-state switching devices, the dc motor was the dominant electric machine for all variable-speed motor drive applications. However, the “power electronic revolution” has led to a significant shift from dc motor drives to adjustable-speed induction motor drives in the low integral to midrange horsepower variable-speed applications for new products.

The dc motor retains niches on either end of the power spectrum where it is still a machine of choice. For instance, the dc motor turns out to be the most economical choice in the automotive industry applications such as cranking, windshield