



## **DEVELOPMENT OF AN AUTOMATIC WHITEBOARD ERASER**

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## **ACKNOWLEDGEMENT**

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## **ABSTRACT**

This project involved the development of conceptual ideas and initial designs layouts of a new Automatic Whiteboard Eraser mechanism. The mechanism is developed to be fast, easy to assemble and dissemble, can be install on any existing wall mounted whiteboard, manufacturable and low cost. Two programmes are developed using Microsoft Excel Spreadsheet to select and sizing the mechanism components. A working model of the developed mechanism was constructed to test its effectiveness.

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## **1.0 INTRODUCTION**

### **1.1 Background Of Project**

Generally, a hand-held fabric eraser is usually used to erase characters written on a whiteboard. However manually cleaning of a whiteboard especially the bigger and longer one is very slow and tedious.

In order to overcome these situations, numerous types of auto erasing mechanism have been proposed by students from local institutions (polytechnics, UNITEN, UiTM, etc). Auto erasing mechanism proposed by UNITEN students use Cartesian robot to moves back and forth, horizontally on a whiteboard. Even though it sounds sophisticated, the cost is too high, which is superfluous for erasing a whiteboard.

This project was intended to provide an alternative of the existing automatic whiteboard erasing mechanism.

### **1.2 Objective Of Project**

The aim of this project is to develop a new Automatic Whiteboard Eraser Mechanism that has the following specifications:

- Fast
- Can be install on any existing wall mounted whiteboard
- Easy to assemble and dissemble
- Manufacturable
- Low cost