FUZZY BASED INTELLIGENT CONTROL SYSTEM FOR ELEVATOR

This report is present in partial fulfillment for the award of the Bachelor of Electrical Engineering (Honours) Of UNIVERSITI TEKNOLOGI MARA (UITM)



MOHD NORHASLAN BIN ALIAS FACULTY OF ELECTRICAL NGINEERING UNIVERITI TEKNOLOGI MARA 40450 SHAH ALAM, SELANGOR

ACKNOWLEDGEMENT

In the name of Allah the most Beneficent and Merciful. A deep sense of thankfulness to Allah who has given me the strength, ability and patience to complete this project and thesis as it is today.

Firstly, I would like to take this opportunity to put into words my deepest gratitude and appreciation to the project supervisor, Puan Jamilah Binti Karim for her support, guidance, patience, encouragement and abundance of ideas during the completion of this project.

Secondly, special thanks to both honorable panels, Puan Hassimah bt Hashim and Dr Fauziah Bt Sulaiman for their comments, invaluable suggestions and outstanding deliberations to improve the project during the project presentation. I would also like to express my extraordinary appreciation to my family for their invaluable support along the duration of my studies until the completion of this thesis.

Finally yet importantly, thanks to all the persons who are directly or indirectly contributed because their perspective and guidance helped greatly to point me in the right direction until the completion of this thesis.

Mohd Norhaslan Bin Alias Faculty of Electrical Engineering Universiti Teknologi Mara (UiTM) Shah Alam, Selangor Darul Ehsan

ABSTRACT

This paper presents the idea to make elevator more efficient for user. This project call video based intelligent control system in elevator. This idea use video based intelligent control system to control the elevator at all time and fuzzy logic based expert system for controlling signal at an intersection. The video can monitor and capture picture at all level then send to system to control the elevator. Both are using MATLAB toolboxes for image acquisition, image processing and fuzzy logic. In this paper only focus on the rule base fuzzy logic. The main objective for this idea is to help people to minimize the waiting time for waiting elevator and also to find solution for efficient dispatch system. It contains of two system monitory it from the key dispatching and video camera. To make it intelligent, fuzzy logic in the MATLAB is use to create rule for this system. By developing the video based intelligent control system for elevator, the time for waiting elevator can be minimize. The result obtained from fuzzy logic simulation

Index Terms- elevator, video based intelligent control system using camera, camera, elevator control system, fuzzy logic

TABLE OF CONTENTS

CHAPTER 1		
INTRODUCTION		1
1.1	OBJECTIVES	2
1.2	SCOPE OF WORK	3
1.3	THESIS ORGANIZATION	3
CHAPTER 2		
LITERATURE REVIEW		4
2.1	INTRODUCTION	4
2.2	THE ELEVATOR ALGORITHM	5
2.3	COMPUTER DISPATCHED	5
2.4	SUPERVISORY CONTROL FOR ELEVATOR	7
2.5	INTRODUCTION TO FUZZY LOGIC & FUZZY CONTROL	9
2.6	FUZZY CONTROL IN DETAIL	11
2.7	FUZZY LOGIC MATLAB TOOLBOX	20
	2.7.1 INTRODUCTION	20
	2.7.2 BUILDING A FUZZY INFERENCE SYSTEM	20
CHAPTER 3		
METHODOLOGY		23
3.1	FUZZY INTERFERENCE SYSTEMS	23
3.2	VIDEO BASED ELEVATOR CONTROL SYSTEM	25
3.3	ELEVATOR CONTROLLER SYSTEM	28
CHAPTER 4		
RESULT AN	D DISCUSSION	35
CHAPTER 5		
CONCLUSION		40
5.1	FUTURE RECOMMENDATION	41
CHAPTER 6		
REFERENCES		43

CHAPTER 1

INTRODUCTION

Now today there are many building is build in high rising because of the space and trend. Elevators are indispensable high rising buildings because of large number of floors and busy traffic. In a tall building with multiple elevators, it is a notoriously difficult task to control the elevators in the most efficient manner. In general, the objectives of elevator control systems differ from building to building; the most common goals are to minimize passengers' average waiting time, to minimize average riding time, and to balance crowding in elevators. Optimizing an elevator group control system to achieve these objectives is difficult for various reasons, including the following [22]: coordination of multiple cars, constraints on elevators' movements, incomplete information (e.g., after a button is pressed at a floor, it is impossible to know how many passengers are waiting at that floor), unknown passenger traffic patterns, and the existence of special-purpose elevators or floors [24]. In order to deal with these difficulties, conventional elevator group control systems have used fuzzy systems [12], [15], [17], [18] artificial neural networks [19], [14], [16], [23], genetic algorithms [20], [21], [24], etc.

Passenger traffic is conventionally classified into the following four patterns [13], [22], [23]: 1) uppeak traffic most passengers move up from the first floor and downward movements are rare (mostly in the early morning); 2) downpeak traffic most passengers move down to the first floor and upward movements are rare (mostly in the evening); 3) lunchtime traffic many passengers move up from and down to the first floor; and 4) interfloor traffic passengers move up and down freely among several different floors with few specific patterns. Some studies have fully or partially focused on uppeak traffic patterns [13], [19], [22] or on lunchtime traffic patterns [15]. Other researchers [17], [21] have proposed adaptation techniques for dynamic flows, which prepare a set of prespecified traffic patterns in advance and switch between policies appropriate for the specific patterns.