

# **PID CONTROL FOR WATER LEVEL WITH UNREGULATED DISCHARGE FLOW**

This thesis is presented in partial fulfillment for the award of the

Bachelor of Engineering (Hons.) Electrical

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## **ACKNOWLEDGEMENT**

First of all, Ahamdulillah and all praise to The Almighty God, Allah SWT for giving me strength, health and opportunity to me for completing my Final Year Project of “PID Control for Water Level with Unregulated Discharge Flow”. I also would like to thank Madam Zuriati Janin for being the most supporter and guide me during competing this project. From beginning, she gives me motivation and support to enable me to achieve the goal of this project until the completion of this project. I like to express my grateful also to technician in DCS Laboratory , UiTM Shah Alam, Pn. Rosni to guide me for getting the result for open-loop test. She guide and teach me how to run the experiment and how to use the DCS controller. the most challenging part in this project is to get the result for unregulated discharge flow in DCS laboratory. The process response must meet the set-point. Thanks to Madam Zuriati and my friend RisznaFisah to help me during the experiment. During completion of the project I gained some valuable knowledge about the process control and Matlab Simulink. Last but not least, I would like to thank my parents, family members, friends and whoever that involves in making this project success.

## **ABSTRACT**

This paper is to identify the best control parameters and structure for controlling water level of the trainer system that located at the DCS laboratory UiTM Shah Alam. In this work, the parameter of the controller is adjusted using Ziegler-Nichols tuning method. The best control structure is analyzed by considering the rise time, settling time, overshoot and steady state error. The result showed that the water level integrating process can best control using PID with parallel structure.

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# CHAPTER 1

## INTRODUCTION

### 1.1 BACKGROUND STUDY

Unregulated Discharge Flow can be define as self-regulating process. This is an unstable process which the principle characteristic is it naturally seeks a steady-state operating level for a period of time at constant controller parameters

To measure the process response, a reaction curve graph of the process been measured. This is obtained from an experiment conducted based on the unstable process. In this project, first order model is used. A first order process has an exponential response to a process step change and can be completely characterized by three parameters: dead time, time constant and gain. The first order model can be represented with:

$$G(s) = \frac{Ke^{-Tdds}}{Tc+1}$$

To control the process, a controller will be used. There are many controller exist but for this process, PID controller is used. It been used because PID controller is the most commonly used in a process. PID controller used due to the possibility of making the