

PROTOTYPE DESIGN COLLECTION

SERIES 2



Prototype Design Collection

Series 2



AHMAD NAJMIE RUSLI

**UNIVERSITI TEKNOLOGI MARA CAWANGAN JOHOR
KAMPUS PASIR GUDANG**

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CHIEF EDITOR:

Ahmad Najmie Rusli

CONTENT EDITORS:

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Hazriel Faizal Pahroraji

Norhisyam Jenal

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Radzi Abdul Rasih

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Tel: +60 7-381 8493

FOREWORD

This digital book on Prototype Design Collection Series 2 (PDC Series 2) is published as a reference design for mechanical engineering students. The designs presented experience a few phases of analysis before fabrication of prototype. Each project summarises the project description, prototype, figures, and design parameter. The design products vary in tools or equipment for household, workshop, entrepreneur, etc. Suggested material and detail of prototype dimension are also mentioned in this book.

It is hoped that this book will assist the students to have more ideas on innovation design products in the future.

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CHAPTER 9

Design, Analysis and Fabrication of Loose Oil Palm Fruit Picker

Ahmad Amin Zakwan Bin Abu Mawan ¹ and Norjasween Abdul Malik ^{2*}

^{1,2}*Mechanical Engineering Studies, College of Engineering, Universiti Teknologi MARA
Johor Branch, Pasir Gudang Campus, 81750 Masai, Bandar Seri Alam, Johor Darul Ta'zim.*

**Corresponding author (e-mail): norjasween@uitm.edu.my*

PROJECT DESCRIPTION

The oil palm industry has been a significant contributor to Malaysia's national economy and commodity exports. However, a major issue in this industry is the considerable amount of loose oil palm fruit left to rot on the ground. The objectives of this project are to design, analyze, and fabricate a manual machine capable of collecting all the loose oil palm fruit from the ground. This machine aims to save time for users by eliminating the need for manual hand-picking. It operates on a mechanical mechanism, utilizing a chain and conveyor system. Users simply need to push a handle to start the machine. The wheel and bearing mechanism are designed to be suitable for use on uneven surfaces, particularly in oil palm plantations. In conclusion, the product has been successfully designed, analyzed, and fabricated. Extensive product testing has been conducted, demonstrating its ability to collect up to 9kg of loose oil palm fruit per session. This product is expected to offer numerous benefits, particularly to oil palm plantation operators, by streamlining their work and maximizing the utilization of valuable loose oil palm fruit.

Keywords: *Oil palm, Fruit picker*

PROTOTYPE



DESIGN PARAMETER

