UNIVERSITI TEKNOLOGI MARA

DESIGN OF SERIAL PERIPHERAL INTERFACE WITH FLEXIBLE MODES AND FREQUENCY FOR ADVANCED MICROCONTROLLER BUS ARCHITECTURE-ADVANCED PERIPHERAL BUS INTERFACE

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ABSTRACT

The model and design of the intellectual property (IP) core of serial peripheral interface (SPI) with Advanced Microcontroller Bus Architecture (AMBA) - Advanced Peripheral Bus (APB) interfacing are presented. The objectives of the project are to model and design a SPI that is interfacing with IP core of APB for sending and receiving data from a single slave to model APB-SPI controller with controllable data and designed with maximum operating frequency of 16 MHz and flexibility in all four clocking modes and finally to synthesize and validate the model of the SPI design. For this work, research regarding interfacing SPI with another core and designing the SPI itself is essential for the project. The design and simulation of SPI master and slave is based on Verilog coding. The Verilog code is the main language that is use for designing and running simulations for this project. SPI is one of the commonly used serial protocols that can send or receive data from a single or multi-slave. Due to proliferation of communication protocols and requirement of flexibility in communication, this work shows how an architecture of APB-SPI controller with controllable data width and an operating frequency of 16MHz is designed. The SPI is simulated, verified, synthesized, carry a layout design and routed using tools such from the electronic design automation (EDA) tools which is Synopsys, simulation software which are ModelSim and Quartus prime lite. The design and implementation of SPI model interface is targeted to be used in Low Power Wireless Microcontroller Unit and its specification is based on Nordic Wireless RF System on Chip. The modes of SPI also play important role in this work where this protocol can run through four modes that corresponds to four possible clocking configurations. The results showed that the core of SPI was successfully modelled and designed with maximum operating frequency of 16 MHz and flexibility in all four clocking modes. The ASIC design of this work consumed an area of 27750 μm2 and a power of 47.12μW by using Silterra 0.18μm for future fabrication CMOS process.

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TABLE OF CONTENTS

CON	FIRMA	ATION BY PANEL OF EXAMINERS	ii
AUTHOR'S DECLARATION			iii
ABSTRACT ACKNOWLEDGEMENT TABLE OF CONTENTS LIST OF TABLES LIST OF FIGURES			iv
			v
			vi
			ix
			x
LIST	OF SY	MBOLS	xii
LIST	xiii		
CHA	PTER (ONE: INTRODUCTION	1
1.1	Resea	rch Background	1
1.2	Proble	em Statement	3
1.3	Objec	tives	4
1.4	Scope	e and Significance of Study	4
1.5	Thesis	s Organization	5
СНА	PTER	TWO: LITERATURE REVIEW	7
1.6	Introd	luction	7
1.7	SoC A	And Bus Protocols.	7
1.8	SPI Protocols		8
	1.8.1	Functional Description	9
	1.8.2	SPI Data Transmission	10
	1.8.3	Key Features of SPI	14
1.9	Implementation of SPI		17
	1.9.1	Implementation of SPI-APB	19
	1.9.2	SPI Applications	20
1.10	Summ	nary for Serial Peripheral Interface	22

СНА	25	
1.11	Introduction	25
1.12	Description of the Methodology	25
1.13	SPI Architecture	27
1.14	SPI Design & Modelling	28
	1.14.1 SPI Master Controller	28
	1.14.2 Control Register	29
	1.14.3 Status Register	30
	1.14.4 Clock Generator	31
	1.14.5 SPI Testbench	33
1.15	Simulation and Validation Process	33
1.16	ASIC Design Process	34

CHAPTER FOUR: RESULTS AND DISCUSSION ON THE SPI DESIGN.		
1.17	Introduction	36
1.18	SPI Master Controller Results	36
1.19	Integration of SPI - APB interface with Clock Generator and Slave	40
1.20	Clock Generator Results	41
1.21	Results of Multi-Modes SPI	42
	1.21.1 Mode 0	42
	1.21.2 Mode 1	43
	1.21.3 Mode 2	44
	1.21.4 Mode 3	45
1.22	Design Compiler (Dc) Analysis Results	46
	1.22.1 Block Diagram of the SPI using DC	46
	1.22.2 Report Scripts from The Design Compiler.	48
1.23	Synopsys Astro Results	52