UNIVERSITI TEKNOLOGI MARA

TECHNICAL REPORT

LEARNING SHORTEST PATH IN LEGO MINDSTORMS EV3 BY USING LINEAR PROGRAMMING

P56518

MUHAMMAD LUQMAN BIN JAMALUDIN MUHAMAD ILHAM ASYRAF BIN SULAM NUR SYAZWANI SYAKIRAH BINTI MOHAMAD HIDZIR

Bachelor of Science (Hons.) (Mathematics)
Faculty of Computer and Mathematical Sciences

DECEMBER 2018

ACKNOWLEDGEMENTS

IN THE NAME OF ALLAH, THE MOST GRACIOUS, THE MOST MERCIFUL. Firstly, Alhamdulillah. We are thankful to Allah S.W.T for His Faithfulness and giving us the strength to complete this Final Year Project, MSP 660 (Teaching and Learning Shortest Path in LEGO Mindstorms EV3 by using Linear Programming) successfully.

We would like to express our gratitude and deepest appreciation to our dearest final year project supervisor, Abdul Rahman Bin Mohamad Gobil, MAT 530 and MSP 660 lecturer, Dr Mat Salim Bin Selamat for their continued support, encouragement and generous guidance in order to see the progress of our project from its initial phase till its completion. The knowledge they shared with us, guidance and their willingness to share time with us and also to never move over on us ease the completion of the Final Year Project.

It is honest and polite to give a tone of appreciation and of thanks to those masses who have assisted in the task. Last but not least, thanks for those who have been contributed for their cooperation, encouragement, constructive suggestion and full support until we managed to complete this project.

TABLE OF CONTENTS

AC	CKNOWL	EDGEMENTS	i
TA	BLE OF	CONTENTS	ii
LIS	ST OF TA	BLES	iv
LIS	ST OF FIG	GURES	v
ΑĒ	BSTRACT	`	vi
1.	INTROD	DUCTION	1
	1.1 PRO	DBLEM STATEMENT	2
	1.2 OBJ	JECTIVES	2
	1.3 SIG	NIFICANCE AND BENEFIT OF THE PROJECT	3
	1.3.1	SIGNIFICANCE OF THE PROJECT	3
	1.3.2	BENEFIT OF THE PROJECT	3
	1.4 SCC	OPE AND LIMITATION OF THE PROJECT	4
	1.4.1	SCOPE OF THE PROJECT	4
	1.4.2	LIMITATION OF THE PROJECT	4
	1.5 DEI	FINITION OF TERMS AND ABBREVIATION	5
2.	BACKG	ROUND THEORY AND LITERATURE REVIEW	7
Ē	2.1 SHO	ORTEST PATH	7
	2.2 LIN	IEAR PROGRAMMING MODEL	8
	2.3 PRI	EVIOUS METHODS USED IN SHORTEST PATH	10
	2.3.1	Dijkstra's algorithm	10
	2.3.2	Linear Programming	11
	2.3.3	Fuzzy Logic	13
	2.4 API	PLICATION AREA OF SHORTEST PATH	14
	2.4.1	Network	14
	2.4.2	Transportation	15
	2.4.3	Navigation and Routing	16
	2.5 TEA	ACHING AND LEARNING LINEAR PROGRAMMING	18
	2.5.1	Tools used in teaching and learning of Linear Programming	18
	2.5.2	Challenge in teaching and learning the Shortest Path Algorithm	19

3.	METHODOLOGY			
	3.1 INTRODUCTION	20		
	3.1.1 Identify Difficulties in Learning Linear Optimization	21		
	3.2 EV3 PROGRAM DEVELOPMENT	22		
	Step 1: Robot Installation and Map Creation	23		
	Step 2: Sensor Testing	23		
	Step 3: Data Collection			
	Step 4: Data Analyse	25		
	Mathematical Formula			
	Step 5: Analyze the Result	28		
	3.3 NUMERICAL EXAMPLES	31		
4.	RESULTS AND DISCUSSION	33		
	4.1 INTRODUCTION	33		
	4.2 RESULTS AND DISCUSSION	33		
	4.3 VALIDATION/PERFORMANCE EVALUATION	39		
5.	CONCLUSIONS AND RECOMMENDATIONS	42		
	5.1 CONCLUSION	42		
	5.2 RECOMMENDATION	43		
RE	REFERENCES			
ΛD	ADDENDIV			

ABSTRACT

Shortest path problem is about finding. It can be utilized to find directions between navigation and path selection, physical locations and see the additional path in the sector. In order to make students more understanding about the course and how to apply the knowledge in the real world, this study strives to apply the Linear Programming method in learning shortest path problems by using LEGO Mindstorms EV3 as the tool to collect data and Microsoft Excel Solver to solve the problem by using Network Simplex method in Linear Programming. This study had used two types of sensors to collect the data from reading of LEGO Mindstorms EV3 on the track. The outcomes indicate that the minimum distance of the shortest path can be obtained by using Linear Programming model. Hence, this study is also able to find the minimization cost of the shortest path by using Linear Programming model. In the future study, it is endorsed to use Python as the tool to solve Linear Programming because the value that obtained is more accurate than other tools solver.