UNIVERSITI TEKNOLOGI MARA

RELIABILITY STUDY OF TERRESTRIAL LASER SCANNER MEASUREMENT FOR BUILDING MAPPING

MUHAMMAD SYAWAL BIN SABRI

Dissertation submitted in fulfillment of the requirements for the degree of Science Surveying and Geomatic (AP220)

Faculty of Architecture, Planning and Surveying

August 2020

AUTHOR'S DECLARATION

I declare that the work in this disertation was carried out in accordance with the regulations of Universiti Teknologi MARA. It is original and is the results of my own work, unless otherwise indicated or acknowledged as referenced work. This thesis has not been submitted to any other academic institution or non-academic institution for any degree or qualification.

I, hereby, acknowledge that I have been supplied with the Academic Rules and Regulations for Post Graduate, Universiti Teknologi MARA, regulating the conduct of my study and research.

Name of Student : Muhammad Syawal Bin Sabri

Student I.D. No. : 2017800088

Programme : Degree in Surveying, Science and Geomatic – AP220

Faculty : Architecture, Planning and Surveying

Thesis : Reliability Study of Terrestrial Laser Scanner

Measurement for Building Mapping

Signature of Student :

Date : August 2020

ABSTRACT

The new evolution of technologies in surveying has focused on developing instruments with the capabilities to provide better accuracy and rapid data acquisition, especially for three-dimensional (3D) measurement purpose. However, due to the consideration that all acquire data are augmented with errors, thus, data quality assurance is compulsory for any proposed application or method regarding the survey jargon. In this study, the concern will be on the reliability of terrestrial laser scanning (TLS) for data acquisition in 3D building mapping. The procedure will be started by establishing a calibration field at the site, where several control points will be established and positioned using total station measurement. Those calibration points will be measured using TLS and analysed to ensure that the calibrated TLS is met the accuracy requirement for building mapping. Next, an appropriate pre-processing network based on the concept of the well-distributed target will be implemented to ensure that the quality of scanned data fulfils the level of detail 4 (LoD-4) measurement. All the data then will be processed in Cyclone Software for the registration and georeferencing procedures. For evaluation purpose, the outputs (from TLS) will be compared with the accurate controlled data which were positioned using total station measurement. The analysis will depict the data quality assurance for 3D point cloud data by the terrestrial laser scanner measurement. In conclusion, this study will present the reliability and optimise procedure for terrestrial laser scanning in 3D building mapping.

TABLE OF CONTENT

CONFIRMATION BY PANEL OF EXAMINERS	i
AUTHOR'S DECLARATION	ii
ABSTRACT	iii
ACKNOWLEDGEMENT	iv
TABLE OF CONTENT	v
LIST OF TABLES	ix
LIST OF FIGURES	X
LIST OF ABBREVIATIONS	xii
CHAPTER ONE INTRODUCTION	1
1.1 Introduction	1
1.2 Problem Statement	2
1.3 Objectives	4
1.4 Research Questions	4
1.5 Significant of Study	5
1.6 Scope of Work	5
1.8 Research Methodology	7
CHAPTER TWO LITERATURE REVIEW	10
2.1 Introduction	10
2.2 Building Mapping	10
2.2.1 Type of Building Mapping	10
2.2.1.1 Strata	10

3.2.	1.1 Data Acquisition	26
3.2.	1.2 Data Processing	27
3.2.2	Phase 2– 3D Network Adjustment Adjustment	27
3.2.2	2.1 Data Acquisition	27
3.2.2	2.2 Data Processing	28
3.2.3	Phase 3– Targets Establishment for Site-Survey Checking	28
3.2.3	3.1 Data Acquisition	28
3.2.3	3.2 Data Processing	29
3.2.4	Phase 4– Coordination of Point for Georeferencing	29
3.2.4	4.1 Data Acquisition	29
3.2.4	4.2 Data Processing	29
3.3 TL	S On-Site Field Checking	30
3.3.1	TLS Field Check Measurement	31
3.3.2	Target Points Registration	31
3.3.3	Dimensional Analysis	32
3.4 TL	S Data Quality Assurance	32
3.4.1	TLS Measurement	33
3.4.2	Registration	33
3.4.3	Georeferencing	34
3.5 Su	mmary	35
CHAP	TER FOUR RESULT AND ANALYSIS	36
4.1 Int	roduction	36
4.2 TL	S On-site Field Checking	36
4.2.1	Preparation of Target Points	36