

# DESIGN AND DEVELOPMENT OF A TURNING SYSTEM FOR FRICTION STIR WELDING OF PIPE

ZURESHAKIM ISMAIL (2006689794)

A thesis submitted in partial fulfillment of the requirement for award of Bachelor Engineering (Hons) (Mechanical)

> Faculty of Mechanical Engineering MARA University of Technology (UiTM)

> > **MAY 2010**

"I declared that this thesis is the results of my own work except the ideas and summaries which I have clarified their sources. The thesis has not been accepted for any degree and is not concurrently submitted in candidature of any degree."

Signed:

<u>||5</u>|| [9/5/10

Date :

#### **ZURESHAKIM ISMAIL**

UiTM No: 2006689794

#### ACKNOWLEDGEMENT

First and foremost, Alhamdulillah and thanks to Allah S.W.T for the completion of this thesis. I am eternally grateful for the support and encouragement from my family. Since the day I entered higher education institution, my family has always inspired and motivates me beyond mere academic mediocrity. During the past year and a half, they had support encouraged me to be more hardworking and steadfast in completing my project. The satisfaction of completion this project is considered as the effort of the family members.

I am also indebt to Mr. Abdul Ghalib Tham as my supervisor, my fellow friends with support and constructive ideas and all the staffs from welding and machine laboratory.

#### ABSTRACT

÷

Friction stir welding (FSW) is one of the latest technologies in the joining of metal. FSW had been popular for welding of plate material particularly aluminum metal. However when come to welding of pipe, the technology is still under research in industrialized countries. One of the essential tools to perform FSW is the requirement of a powerful turning system. It should be able to accommodate a pipe of specific diameter in 1G position, rotated at a specific speed, relevant for FSW applications. Another alternative design is to orbit the stiring tool around the pipe in 5G position.

The turning system for friction stir welding of pipe comprised of a base frame, a cylindrical clamping mechanism for securing a cylindrical work piece, a worm gear, and a dc motor with variables speed. The basic mechanism for this turning system is the dc motor, which drives the worm screw and rotate the worm gear and the worm gear will drive the pipe that will be welded.

This turning system controlled by the speed controller system. The actual welding speed has to select by trial welding. The motor must deliver adequate torque at any selected speed. The current design demonstrated the successful operation of FSW, delivering the required travel speed. The motor power however has to be increased.

ii

## **TABLE OF CONTENT**

CONTENTS	PAGE
ACKNOWLEDGEMENT	i
ABSTRACT	ii
TABLE OF CONTENT	iii
LIST OF TABLES	vii
LIST OF FIGURES	viii

### **CHAPTER 1: INTRODUCTION**

1.0	Overview	1
1.1	Objective	6
1.2	Scope of project	6
1.3	Problem Statement	б