

**INVESTIGATION OF ROBOTIC WELDING PROCESS BY USING
ROBOTSTUDIO™5.10 AND ABB ROBOT**

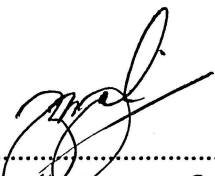
**SHAHFUAN HANIF BIN AHMAD HAMIDI
(2005607728)**

A thesis submitted in partial fulfillment of the requirement for award of Bachelor
Engineering (Hons) Mechanical

Faculty of Mechanical Engineering
MARA University of Technology (UiTM)
40450 Shah Alam,
Selangor Darul Ehsan.

NOVEMBER 2009

“I declare that this thesis is the results of my own work except the ideas and summaries which I have clarified their sources. The thesis has not been accepted for any degree and is not concurrently submitted in candidature of any degree.”

Signed: .....
Date : 24.11.2009.....

Shahfuan Hanif Bin Ahmad Hamidi

UiTM No: 2005607728

ACKNOWLEDGEMENT

Alhamdulillah and thanks to Allah the Almighty with whose Bounty and Mercy, the author had succeeded to complete this project although many problems occur during the processes to complete the project, and also an eternally grateful for the support and encouragement from the author family. I would like to express my sincere gratitude and appreciation to my supervisor Dr. Ing Yupiter HP Manurung for his continuous support, generous guidance, patience and encouragement in the duration of the project preparation until its completion. Moreover, this project would not have been possible without the help of Mr. Ghalib Tham, lecturer of Applied Welding Engineering course and Mr. Mohd Fathi Abdullah, engineer at ABB Malaysia Sdn. Bhd for their assists throughout the entire period of this project. The author also appreciates the efforts of colleagues who have helped and support directly or indirectly for the completion of this project.

ABSTRACT

This project discussed about the investigation of robotic welding using RobotStudio™5.10 Software and ABB Robot. In this project there are two approaches that have been taken, simulation and execution. In simulation, there are several steps need to be carried out. Those are CAD modeling, layout arrangement, and rapid programming which are available on RobotStudio™5.10 Software. The author makes some study cases on this software on basic understanding for the readers. The study cases are including simple geometry for generating rapid program, I/O programming where in creating signal with other devices and advanced rapid programming by creating new movement function. In execution approach, the author executes a rapid programming directly to ABB robot. These activities required some preparation before, during, and after execution. Therefore, the author used example of ship panel structure to adapt all the preparation that need to be carried out. This example is documented together with the suitable welding parameter. In conclusion, by reading this book, readers should have general ideas of basic fundamental in applying in simulation and execution of robotic. They also know about the advantages of the software and the robot itself.

TABLE OF CONTENTS

CONTENTS	PAGE
PAGE TITLE	i
ACKNOWLEDGEMENT	ii
ABSTRACT	iii
TABLE OF CONTENTS	iv
LIST OF TABLES	ix
LIST OF FIGURES	x
CHAPTER I INTRODUCTION	
1.0 Introduction	1
1.1 Background of Project	2
1.2 Objective of Project	2
1.3 Scope of Project	3
1.4 Significance of Project	3
CHAPTER II LITERATURE REVIEW	
2.1 Robotic System – An Overview	4
2.2 Development of Robotic Welding	6
2.2.1 Robotic Programming	7