

Universiti Teknologi MARA

**Tobi-RC Mobile Application:
Development of Remote Control Car
Program over Bluetooth System**

Ain Amirah Binti Hussin

**Thesis Submitted in Fulfilment of the Requirements
for Bachelor of Computer Science (Hons) Faculty of
Computer and Mathematical Sciences**

FEBRUARY 2016

STUDENT'S DECLARATION

I certify that this report and the project to which it refers is the product of my own work and that any idea or quotation from the work of other people, published or otherwise are fully acknowledged in accordance with the standard referring practices of the discipline.

.....

AIN AMIRAH BINTI HUSSIN

2013719621

FEBRUARY 4, 2016

ABSTRACT

Mobile application is trendy and receives high demand in marketplace. Thus, mobile technology has been identified as a potential delivery alternative since it is able to provide services anywhere and anytime. For example, mobile control can control other device via mobile phone just by using the application such as television, air conditioner, lamp and fan. This project develops a mobile control application used to control the movement of the particular control car. This project have achieve three objectives which are to design mobile based program that allows user to play the control car using the smart phone, to develop a program that connects the car over Bluetooth system and to test the functionality of the prototype. The project achieve objectives by using RAD (Rapid Application Development) approach as the guideline and by making sure that this application is filled with great user experiences and functionality goals. This project use fuzzy control for the algorithm and Bluetooth for the technique. The developing of the remote buttons in the android application can control the car motion, interfaced by the Bluetooth module. The significance of this project is users can bring their smart phone without have to carry the remote control. Besides that, the range distance of the control car is 10 meter and suitable for indoor. There are many advantages when use smart phone as a remote control such as portable, does not need to change the battery, low cost and can get wide range of signal better than used telescoping antenna. The mobile application can add acceleration and use gyroscope to control the car as the future improvement.

TABLE OF CONTENT

CONTENT	PAGE
SUPERVISOR'S APPROVAL	ii
DECLARATION	iii
ACKNOWLEDGEMENT	iv
ABSTRACT	v
TABLE OF CONTENT	vi
LIST OF FIGURE	ix
LIST OF TABLE	xii
LIST OF ABBREVIATIONS	xiv
CHAPTER ONE: INTRODUCTION	
1.1 Background Study	1
1.2 Problem Statement	2
1.3 Objective	3
1.4 Scope	3
1.5 Significant	3
1.6 Research Element/Focus	3
1.6.1 The components used	3
1.6.2 The type of programming used	4
1.6.3 Algorithm used	4
1.7 Expected Outcome	4
CHAPTER TWO: LITERATURE REVIEW	
2.1 Overview: Addiction of Control Car	5
2.2 Remote Control	6
2.2.1 Problem of Telescoping Antenna	8

2.2.2	Problem of Battery	10
2.3	Smart Phone and Mobile Application	13
2.4	Programming Language in Android	17
2.4.1	Fuzzy Control Algorithm	18
2.5	Bluetooth Technology	19
2.6	Telescoping Antenna versus Bluetooth Module	25
2.7	Arduino Uno	26
2.8	Related Work	31
2.9	Summary	32

CHAPTER THREE: METHODOLOGY

3.1	Project Framework	33
3.2	Stages of Rapid Application Development	36
3.2.1	Requirement and Planning	36
3.2.2	User Design	38
3.2.2.1	System Architecture	39
3.2.2.2	Storyboard	40
3.2.3	Construction	42
3.2.4	Cutover	42
3.3	Project Timeline	43
3.4	Summary	43

CHAPTER FOUR: DESIGN AND DEVELOPMENT

4.1	User Interface	44
4.1.1	Cover Interface	44
4.1.2	Main Interface	45
4.1.3	Flow of Prototype	47
4.2	Construction	48
4.2.1	Hardware Requirement	48
4.2.1.1	L298 Motor Driver	48
4.2.1.2	Arduino Uno R3	49
4.2.1.3	HC-06 Serial Bluetooth Module	50
4.2.1.4	Wire Connector	51